

# GNSS Spoofing en Detectie

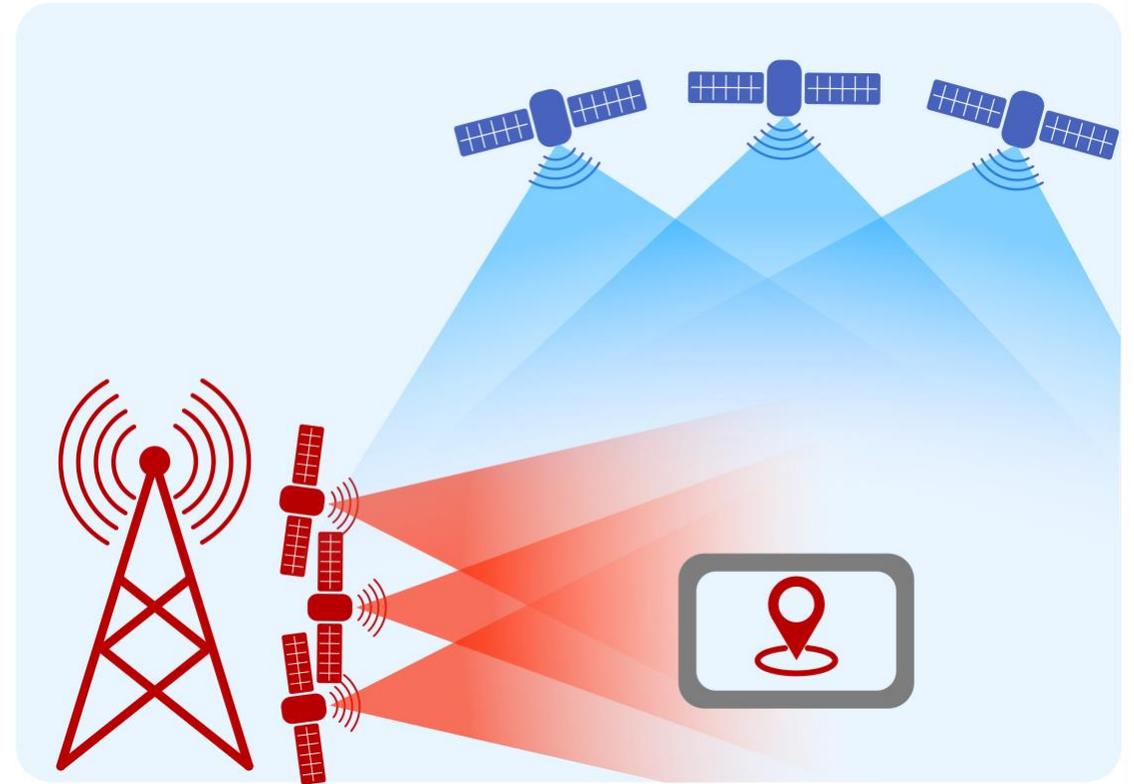
Workshop GNSS Interferentie en Spoofing

Barend Lubbers



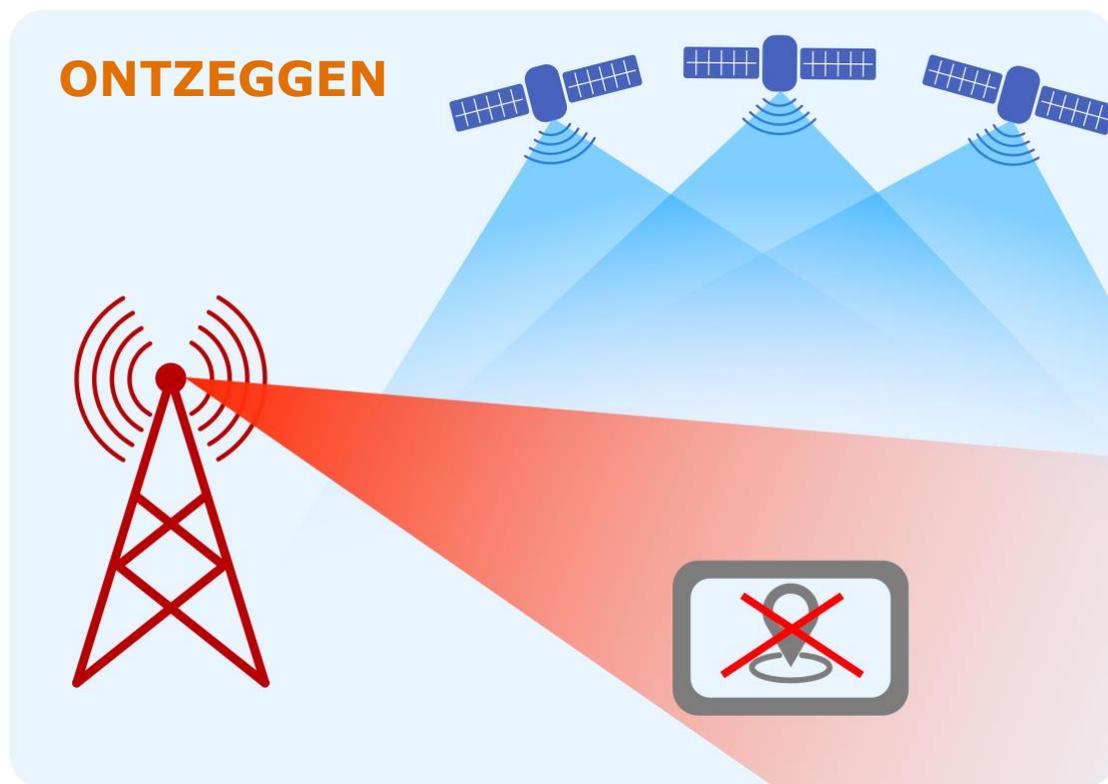
# Spoofting

To assume or emulate the identity of another user or device in order to gain access to a system





# Doel Opzettelijke interferentie





# Onderwerpen



Hoe werkt een GNSS spoofer



Welke types spoofers bestaan er



Hoe kan spoofing worden gedetecteerd?



Van spoofing naar jamming

# GNSS Spoofing: from fiction to reality

James Bond:  
Tomorrow Never Dies:  
Villans spoof HMS  
Devonshire into  
Chinese waters



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# Meaconing





# GPS signaal

Het civiele GPS signaal bestaat uit:

Draag golf

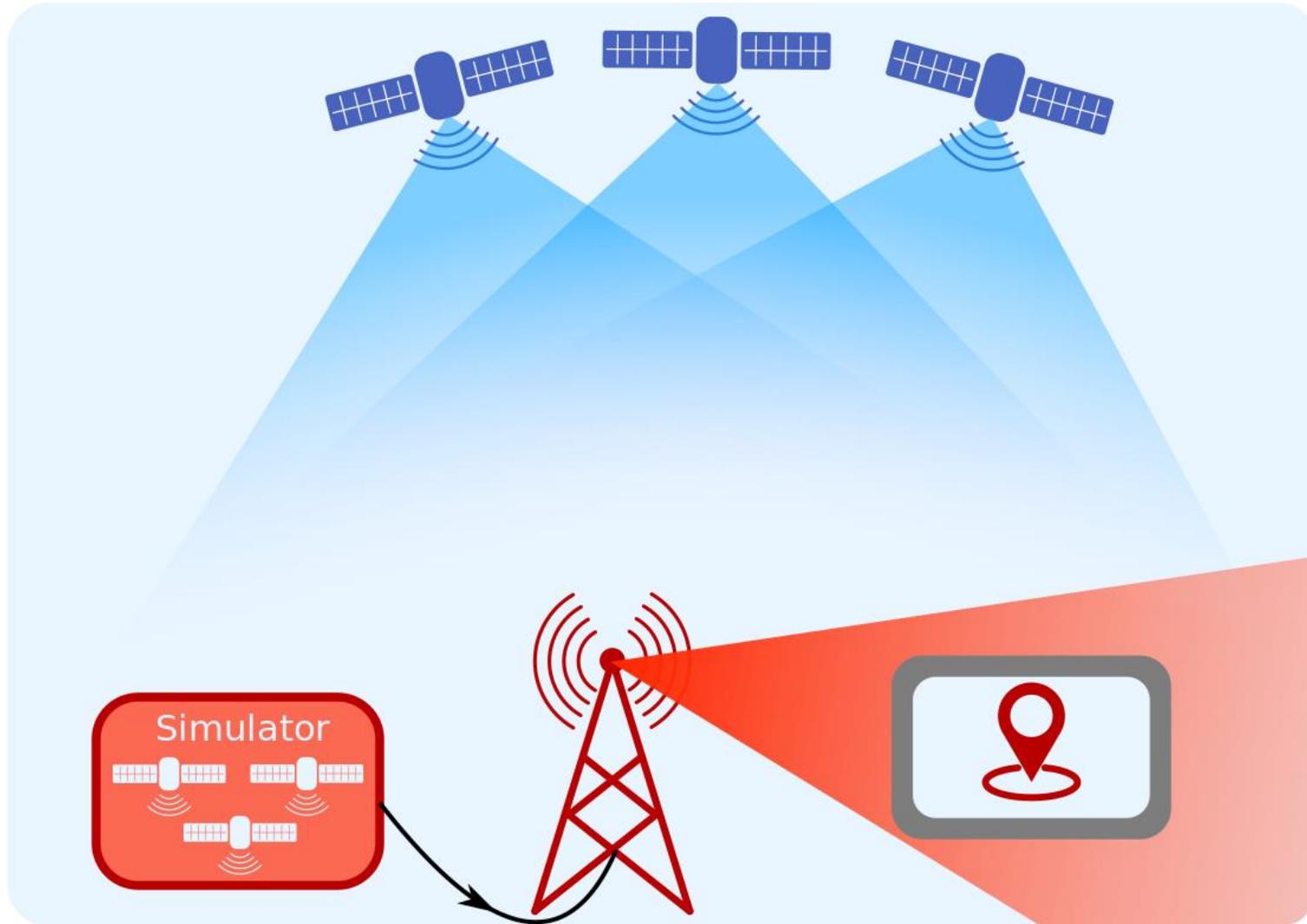
Spreading code

Data bericht

De beschrijving van het signaal is volledig openbaar en vrij verkrijgbaar op internet



# GNSS signaal simulator



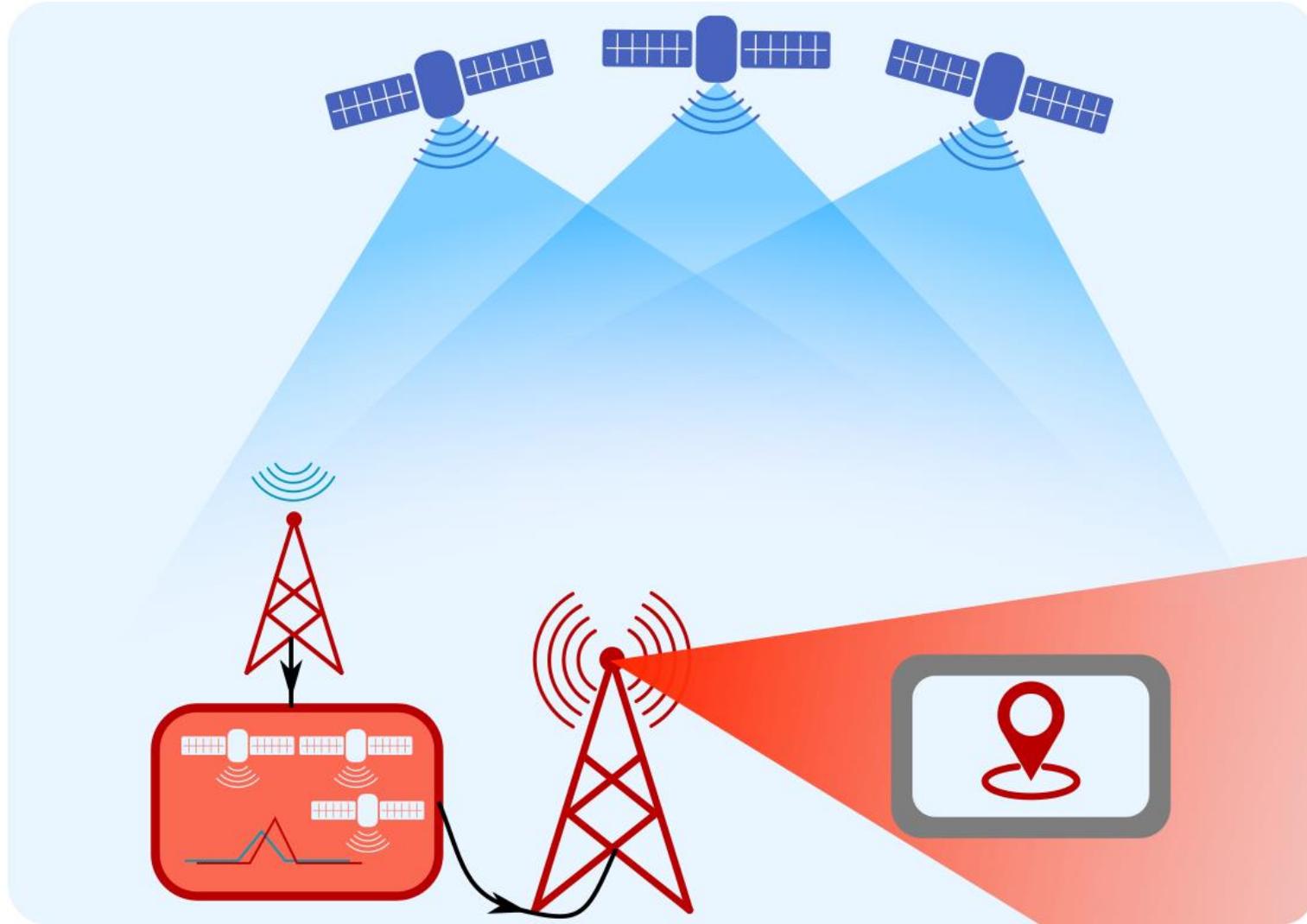


# Meaconing en signaal simulator spoofers

- > Consistente metingen
  - Niet te detecteren met conventionele RAIM technieken
- > Ontvanger alleen kwetsbaar in acquisitie fase
  - Combineren met jammer
  - Loss of Lock

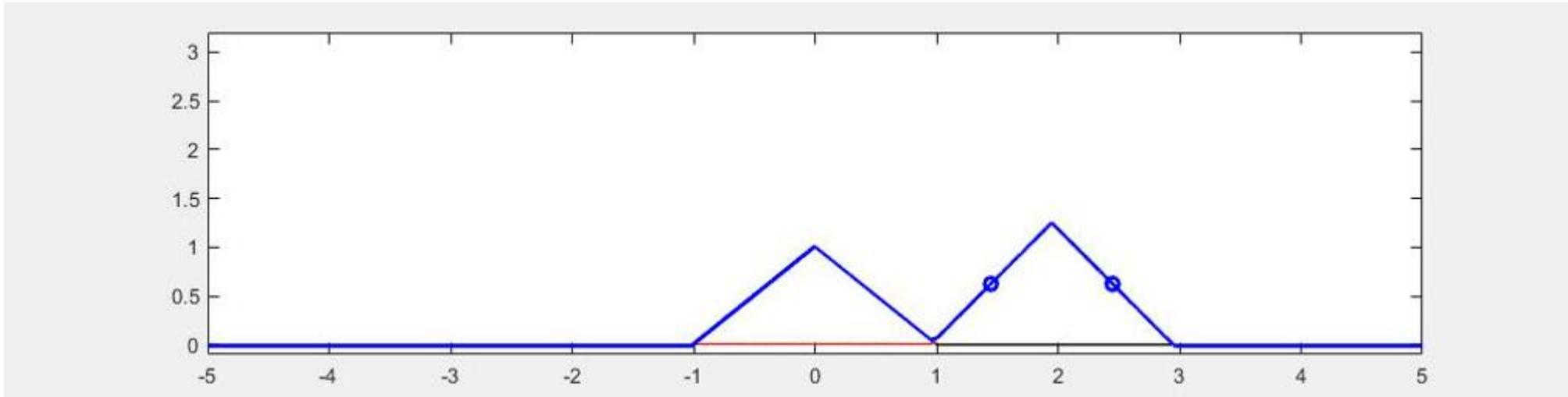


# Seamless take-over





# Seamless take-over spoofer



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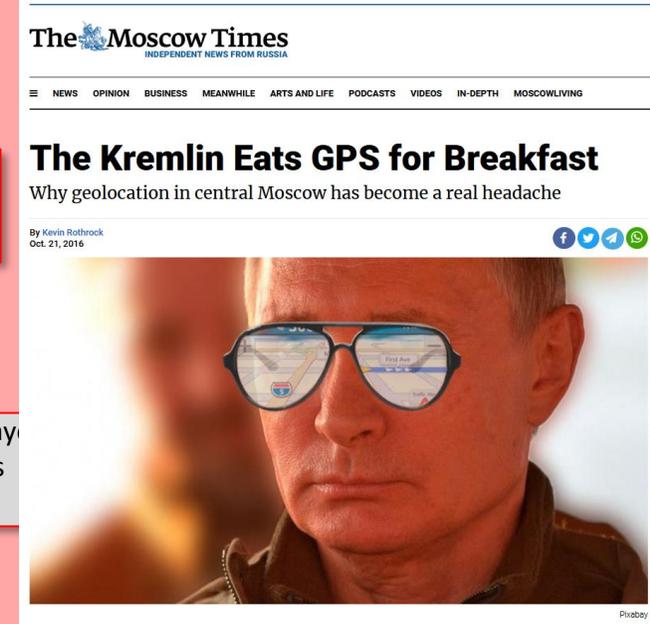
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# Spoofting detectie

## RECEIVER AUTONOMOUS INTEGRITY MONITORING (RAIM)

- > Controleert de consistentie van de metingen
- > Niet effectief tegen de meeste spoofing aanvallen

## ONTVANGEN VERMOGEN

- > Signaal sterkte van het ware signaal is bekend
- > Automatic gain control
- > Realistische  $C/N_0$



# Spoofting detectie

## CONTROLE DATABERICHT

- > Is het bericht complete?  
Almanak etc.
- > Word Error Rate (WER)
- > Navigation Message Authentication (NMA)

## DRIFT DETECTIE

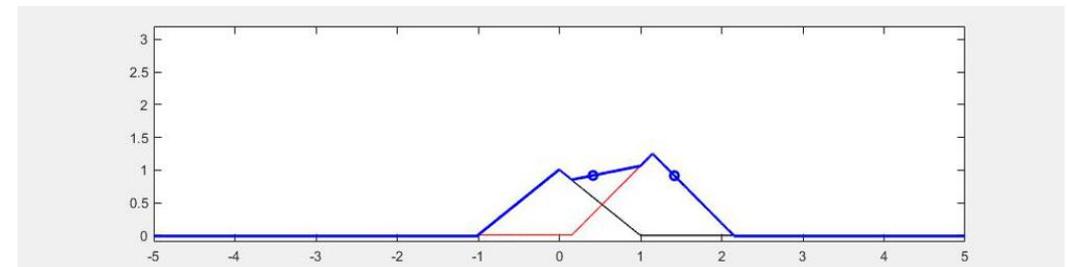
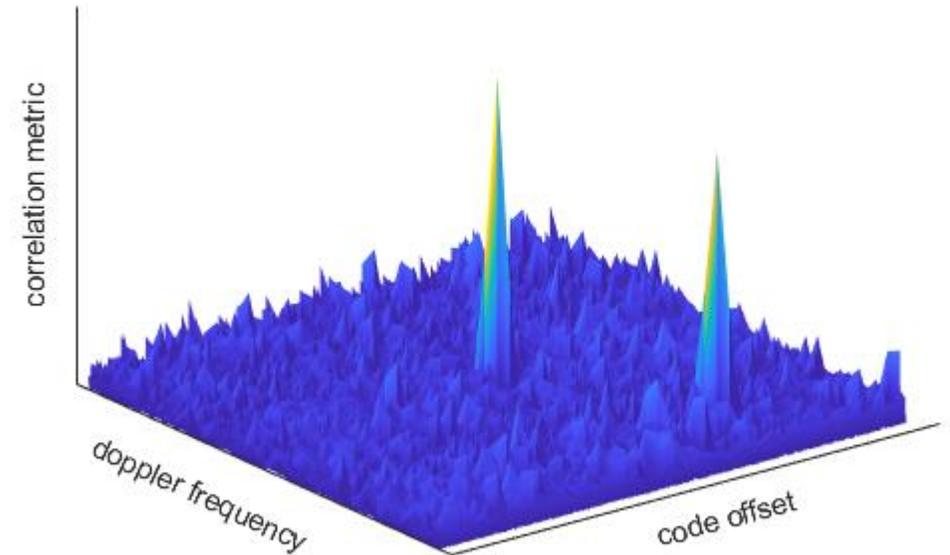
- > Sprong in positie of tijd
- > Onrealistische dynamica
- > Inconsistentie met andere sensoren (IMU, log, etc)



# Spoofing detectie

## AUTOCORRELATIEFUNCTIE

- > Tijdens overname => vervorming van autocorrelatiefunctie
- > Na overname => meerdere correlatie pieken zichtbaar
- > Multipath

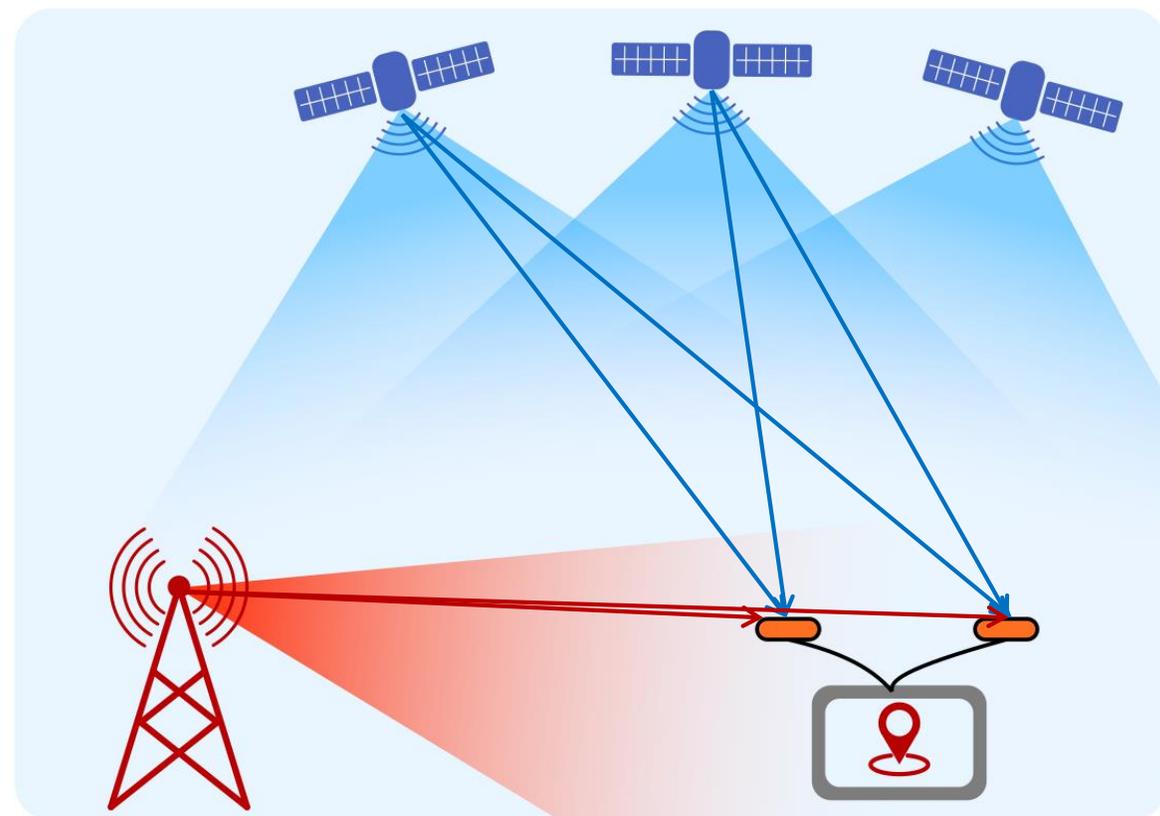




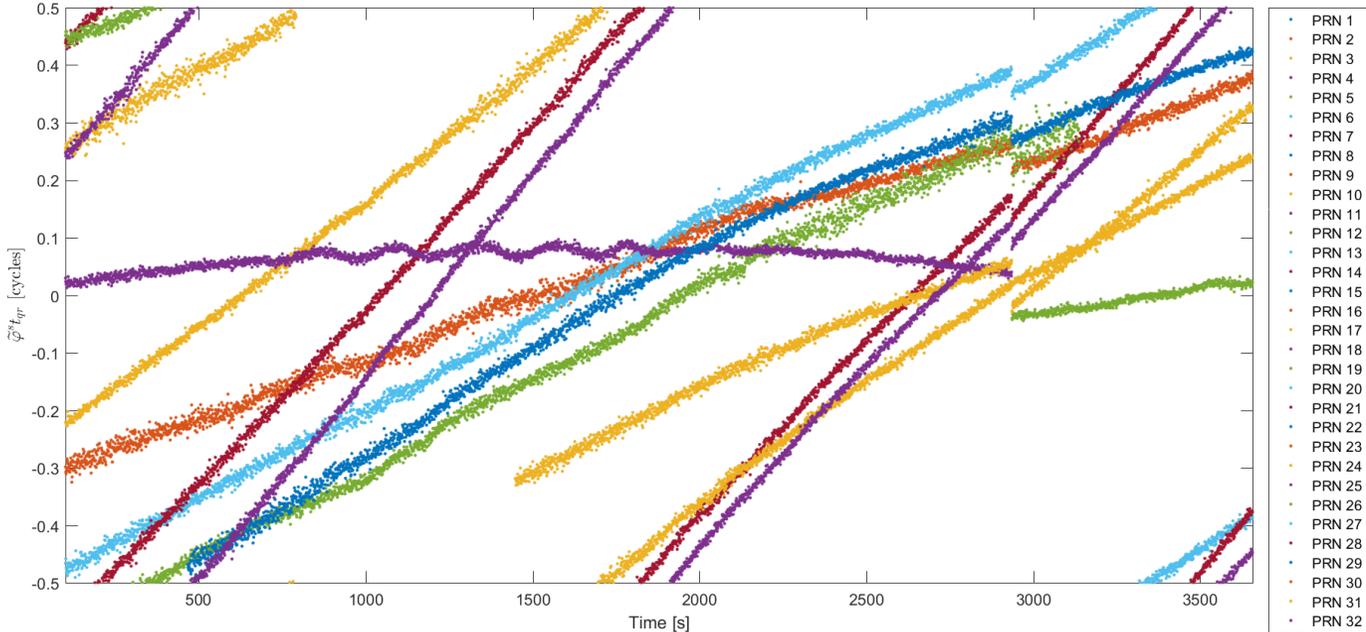
# Spoofting detectie

## ONTVANGER SATELLIET GEOMETRIE

- > Meerdere antennes => angle of arrival
- > Komen de signalen uit de te verwachten richting?
- > Alle signalen uit dezelfde richting => spoofing



**NIET GESPOOFED**



**GESPOOFED**

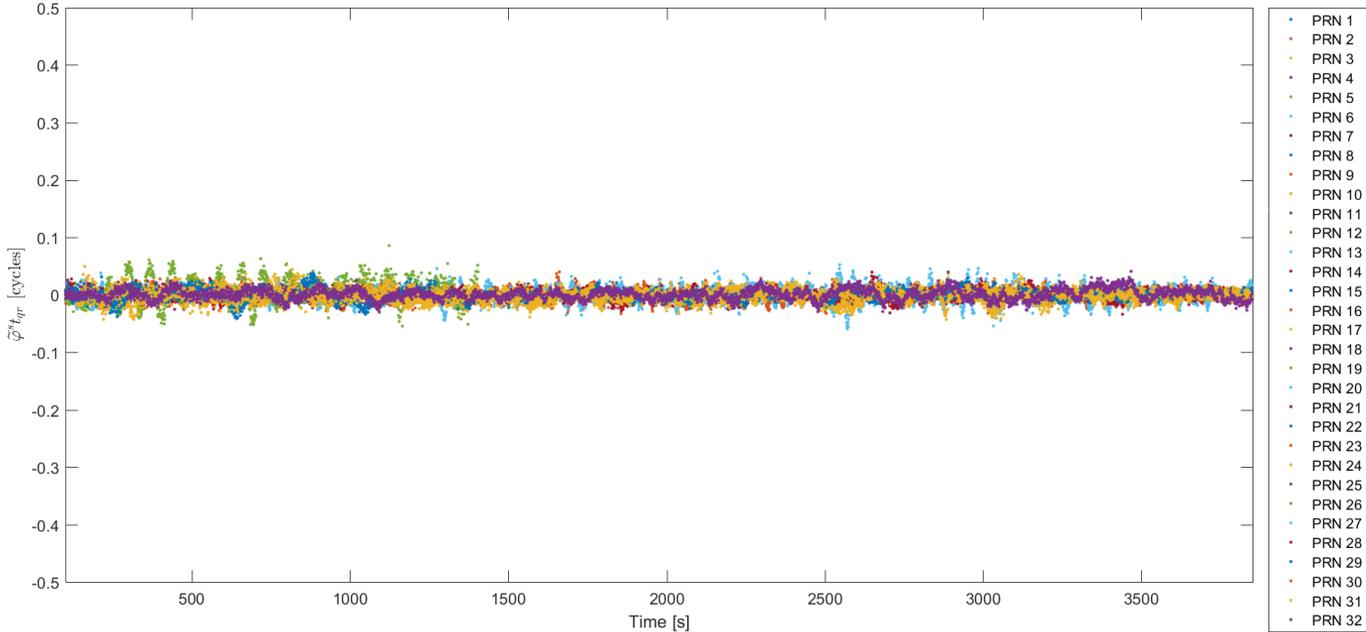


TABLE I: Cost-Ranked Matrix of GNSS Spoofing Attack and Detection Techniques

Detection Techniques	Attack Techniques												
	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	A13
D1	X	X	X	X	X	X	X	X	X	X	X	X	X
D2	~	✓	X	X	~	X	X	X	X	X	X	X	X
D3	~	~	~	~	~	X	X	~	~	~	~	X	X
D4	~	✓	~	~	~	~	~	~	~	~	~	~	~
D5	✓	✓	✓	✓	✓	~	~	✓	✓	✓	✓	~	~
D6	X	✓	✓	X	X	✓	X	✓	✓	X	X	✓	X
D7	X	✓	✓	~	X	✓	~	✓	✓	~	X	✓	~
D8	X	✓	✓	~	X	✓	~	✓	✓	~	X	✓	~
D9	~	✓	✓	✓	~	✓	✓	✓	✓	✓	~	✓	✓
D10	✓	✓	✓	✓	✓	✓	✓	✓	~	~	~	~	~
D11	✓	✓	✓	✓	✓	✓	✓	X	~	~	~	~	~
D12	X	✓	✓	~	X	✓	~	✓	✓	~	X	✓	~
D13	X	✓	✓	~	X	✓	~	✓	✓	~	X	✓	~

Detection probability matrix keys: ✓ – high, ~ – intermediate or case-dependent, X – low

Detection Techniques Key	Attack Techniques Key
D1 Pseudorange-based RAIM	A1 Meaconing, single RX ant., single TX ant.
D2 Observables and RPM	A2 Open-loop signal simulator
D3 Correlation function distortion monitoring	A3 RX/SP, single TX ant., no SCER
D4 Drift monitoring (clock offset, IMU/position)	A4 RX/SP, single TX ant., SCER
D5 Observables, RPM, distortion, and drift monitoring	A5 Meaconing, multi. RX ants., single TX ant.
D6 NMA*	A6 Nulling RX/SP, single TX ant., no SCER
D7 NMA* and SCER detection	A7 Nulling RX/SP, single TX ant., SCER
D8 Delayed symmetric-key SSSC*	A8 RX/SP, single TX ant., sensing of victim ant. motion
D9 NMA*, SCER detection, RPM, and drift monitoring	A9 RX/SP, multi. TX ants., no SCER
D10 Multiple RX antennas	A10 RX/SP, multi. TX ants., SCER
D11 Moving RX antenna	A11 Meaconing, multi. RX ants., multi. TX ants.
D12 Dual-RX keyless correlation of unknown SSSC codes	A12 Nulling RX/SP, multi. TX ants., no SCER
D13 Symmetric-key SSSC* [e.g., P(Y) equiv.]	A13 Nulling RX/SP, multi. TX ants., SCER

\* Detection techniques requiring changes to the Signal In Space (SIS); TX: Transmitter; RX: Receiver; RX/SP: Receiver-Spoofers

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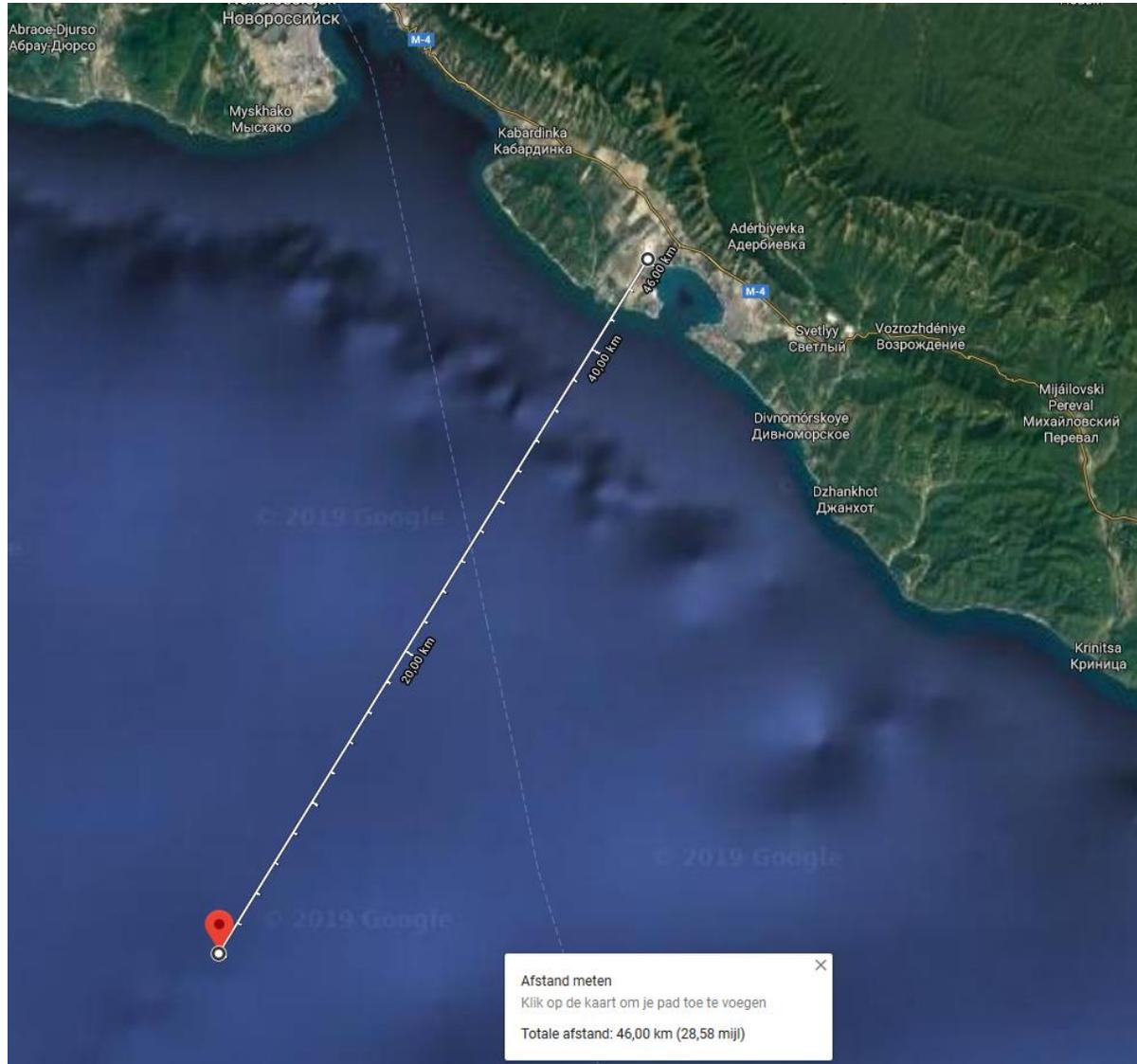
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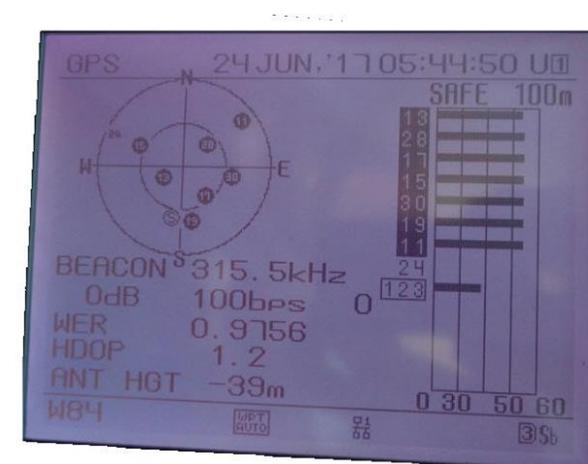
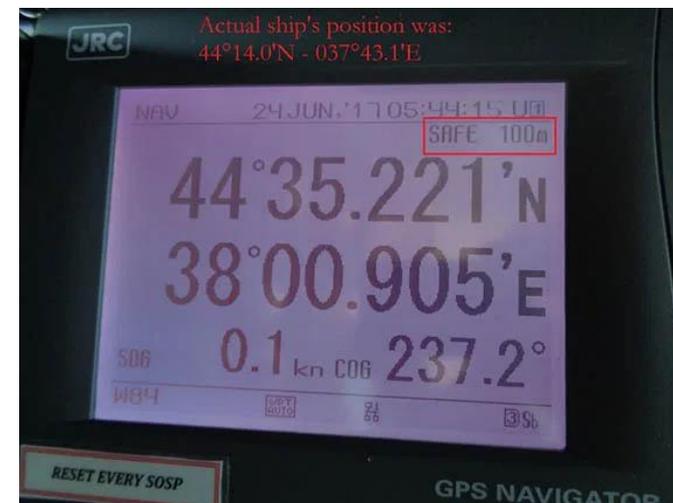


# Zwarte zee, 22 juni 2017



AIS data showing multiple ships on top of each other during their time in the Black Sea

Credit **Gurvan Le Meur**



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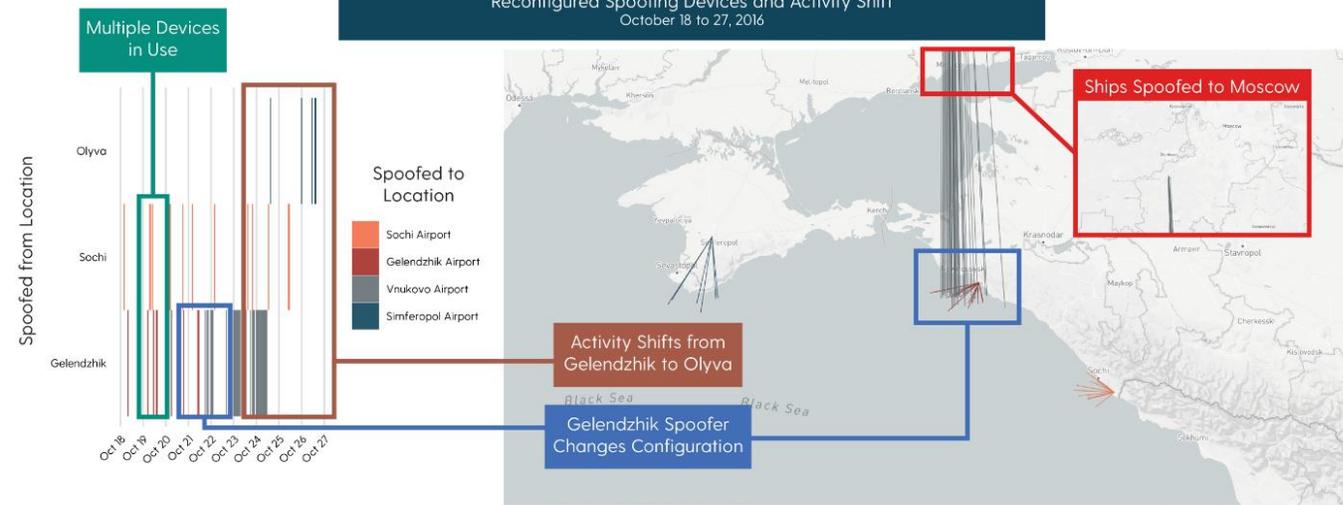
# Above us only stars

## Exposing GPS Spoofing in Russia and Syria

[www.c4reports.org/aboveusonlystars](http://www.c4reports.org/aboveusonlystars)



Reconfigured Spoofing Devices and Activity Shift  
October 18 to 27, 2016



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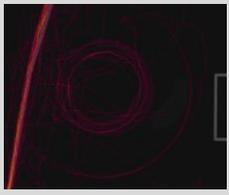
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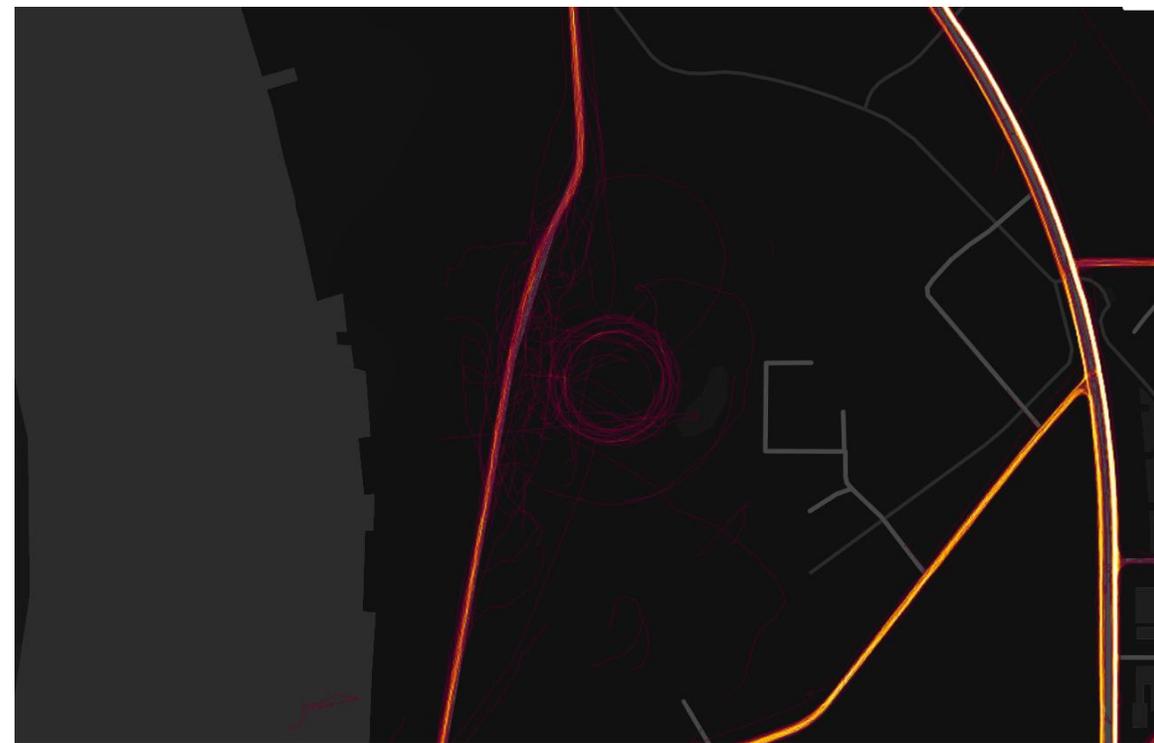
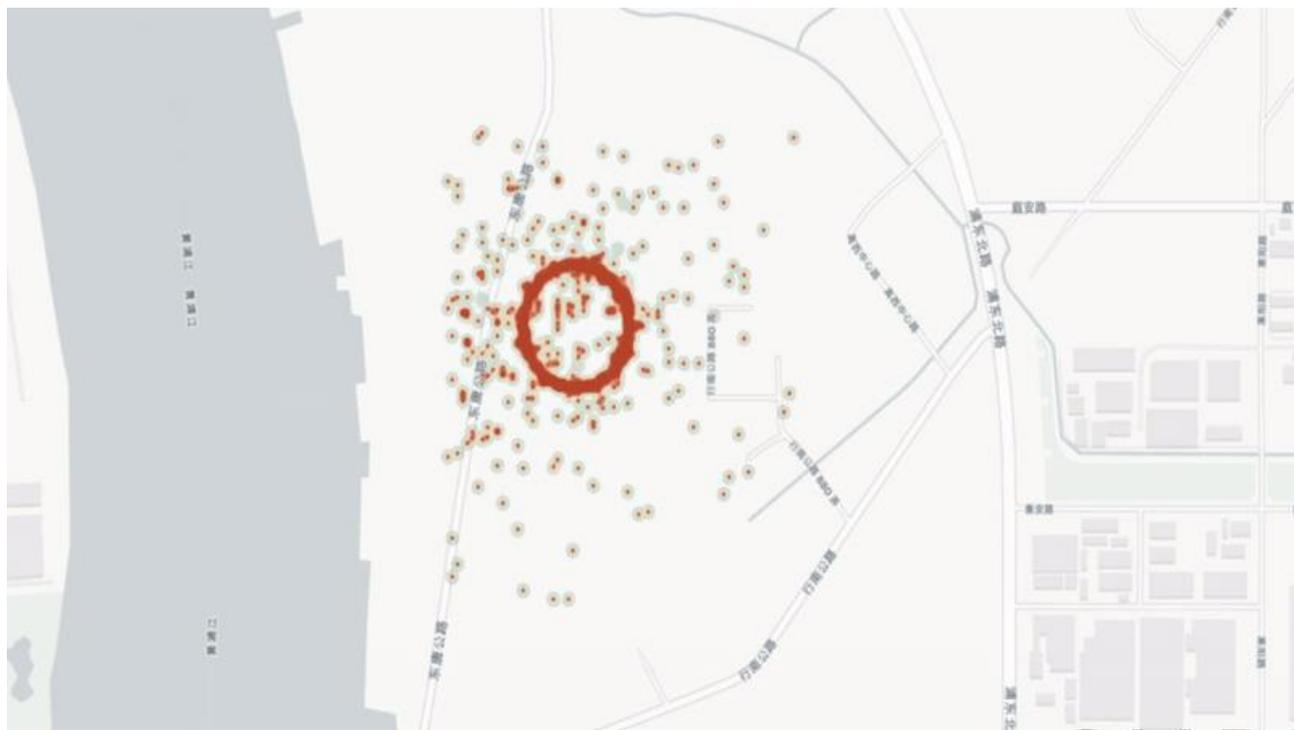
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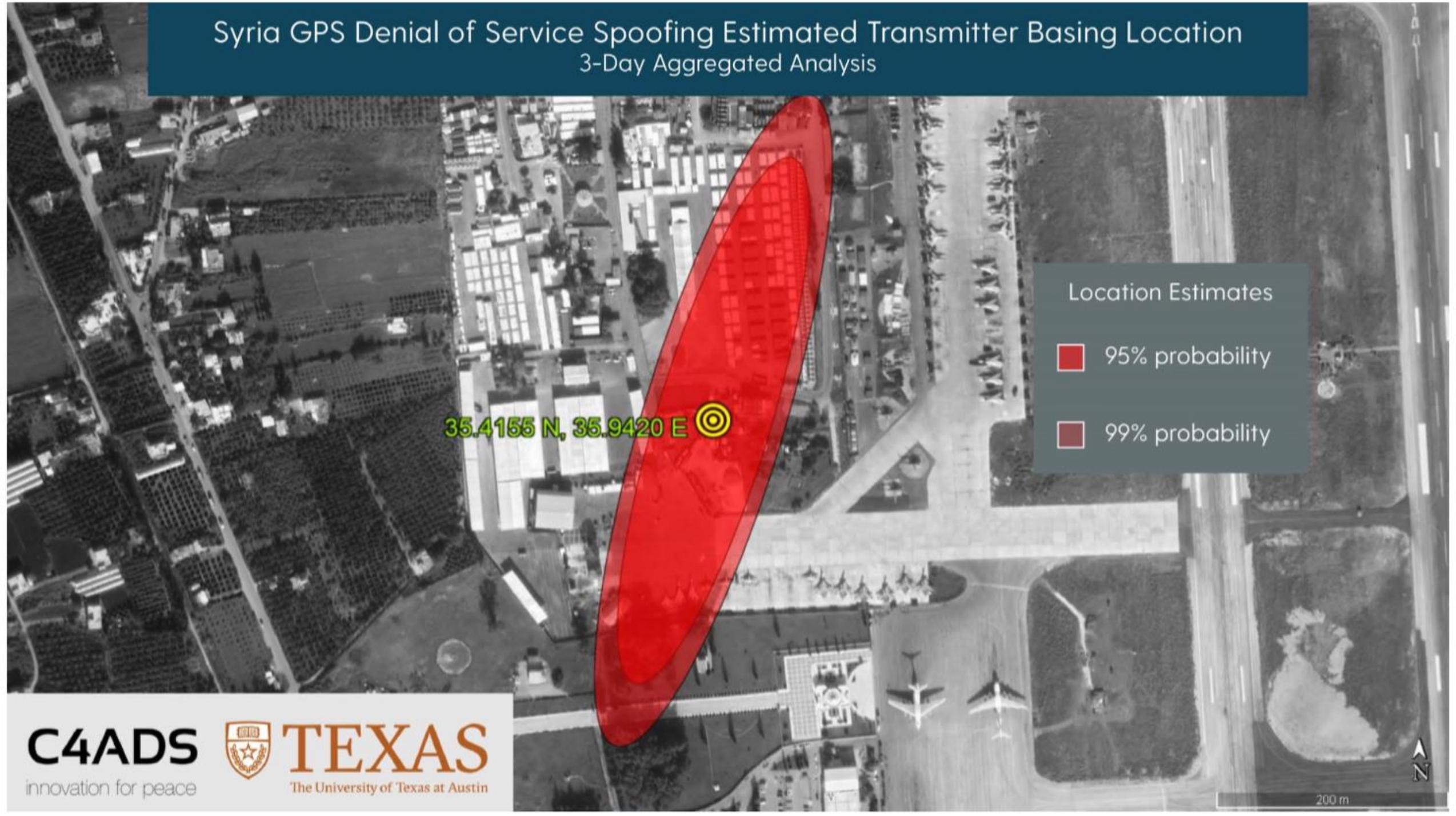


# Shanghai GPS spoofing



# Syria GPS Denial of Service Spoofing Estimated Transmitter Basing Location

## 3-Day Aggregated Analysis





# Jamming meets spoofing

## CONVENTIONELE JAMMER

- > 2 Watt
- > 2 MHz bandbreedte
- > Ontvanger
  - $\left(\frac{C}{N_0}\right)_{\min track} = 25 \text{ dB Hz}$

Bereik  $\sim 15 \text{ km}$  ( $\sim 700 \text{ km}^2$  !!!)

## GECODEERDE JAMMER

- > Jammer genereerd GNSS signalen zonder data
- > Bereik 15 km => 1mW
- > Alleen effectief in acquisitie fase

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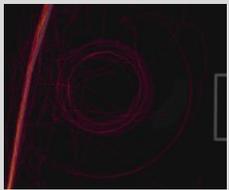
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